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Title:

Anticipatory postural adjustments during cutting manoeuvres in football and their consequences for knee injury risk.

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Running Title:

Anticipative strategies during cutting manoeuvres.

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Abstract

Anticipatory postural adjustments (APA), i.e. preparatory positioning of the head, the trunk and the foot, are essential to initiate cutting manoeuvres during football games. The aim of the present study was to determine how APA strategies during cutting manoeuvres are influenced by a reduction of the time available to prepare the movement.

Thirteen football players performed different cutting tasks, with directions of cutting either known prior the task or indicated by a light signal occurring 850ms, 600ms or 500ms before ground contact.

With less time available to prepare the cutting manoeuvre, the head was less orientated towards the cutting direction (p=0.033) and the trunk was even more rotated in the opposite direction (p=0.002), while the foot placement was not significantly influenced. Moreover, the induced higher lateral trunk flexion correlated with the increased knee abduction moment (r=0.41; p=0.009).

Increasing lateral trunk flexion is the main strategy used to successfully perform a cutting manoeuvre when less time is available to prepare the movement. However, higher lateral trunk flexion was associated with an increased knee abduction moment and therefore an increased knee injury risk. Reducing lateral trunk flexion during cutting manoeuvres should be part of training programs seeking the optimization of APAs.

Introduction

Changing the direction or avoiding obstacles is an integral part of many team sports as for instance football. It is evident that preparatory strategies, so-called anticipatory postural adjustments (APA), are necessary for a successful movement execution (Jindrich & Qiao, 2009; Patla, Adkin, & Ballard, 1999; Xu, Carlton, & Rosengren, 2004). Basically, changing direction requires a reorientation of the body together with the impulse vector to move the centre of mass (CoM) in the direction of the intended movement. This could be achieved by three main strategies involving the whole body. Firstly, the foot placement via the step width regulation plays an important role (Patla et al., 1999; Vallis & McFadyen, 2003; Wheeler & Sayers, 2010). Indeed, the placement of the foot determines the position of the centre of pressure and defines in which direction the CoM can be accelerated (Patla et al., 1999). Secondly, head orientation is used to adjust the visual field and to initiate the reorientation of the whole body (Hicheur, Vieilledent, & Berthoz, 2005; Sreenivasa, Frissen, Souman, & Ernst, 2008; Vallis & McFadyen, 2005). Finally, the control of trunk motion is crucial (Sreenivasa et al., 2008; Vallis & McFadyen, 2005). The trunk yaw (rotation about the long axis of the body) orientates the body in the new direction. Moreover, the trunk roll (lateral flexion) is used to move lower limbs and upper body in opposite directions, which allows moving the CoM towards the new direction during the stance phase (Patla et al., 1999), especially when the change of direction occurs late. It is worth noting that APAs must already be planned and initiated in the step before changing the direction (Patla et al., 1999; Vallis & McFadyen, 2005).

Changes of direction can be performed differently, e.g. side-stepping, cutting or crossover manoeuvres during various sport disciplines. The way APAs initiate and organize the movement (manoeuvrability) influences the performance (Jindrich & Qiao, 2009). For instance it has been reported that higher skilled rugby players demonstrate faster changes of direction than less skilled players (Gabbett & Benton, 2009).

But manoeuvrability is also associated with injury risk (Jindrich & Qiao, 2009). Indeed, lateral movements with changes of direction may lead to misalignments in the lower extremities with the consequence that the knee may be at a relatively high risk of injuries, such as anterior cruciate ligament ruptures (Alentorn-Geli et al., 2009; Olsen, Myklebust, Engebretsen, & Bahr, 2004). As football is the most commonly practiced sport in the world, the injury concern in this activity is even higher than in other sports (Alentorn-Geli et al., 2009), which underlines the need for researchers to keep improving the body of knowledge dealing with knee injury mechanisms and risk factors associated with football practice. Moreover, knee injuries are often experienced in an unpredictable setting, as for instance perturbed landing or insufficient time to prepare the movement (Olsen et al., 2004). Experimental results revealed that knee joint loading, especially knee valgus moment, was greater during unpredictable conditions and consequently may have increased the risk of knee injuries during these cutting manoeuvres (Besier, Lloyd, Ackland, & Cochrane, 2001; Houck, Duncan, & Haven, 2006).

Therefore, the influence of unpredictable conditions on APAs during cutting manoeuvres and their consequences for knee injury risk are of interest. Increasing the body of knowledge dealing with APAs would help to further understand how performance and safety could be improved during such tasks typically encountered during football games. In addition to the unpredictability of the upcoming change of direction, the time available to prepare the movement plays an important role as recently proposed by Brown, Palmieri-Smith and McLean (2009). Although anticipatory postural adjustment strategies have been fairly well described during

changes of direction, their limitations have not been investigated so far during critical situations, i.e. during a cutting manoeuvre with little time available to prepare.

The aim of the present study was to determine which APAs are the most relevant during cutting manoeuvres in football and which fail when time available to prepare the movement is limited. We hypothesized that football players would increase their lateral trunk flexion when the time available to prepare the cutting manoeuvre was reduced. Finally, we aimed to evaluate the consequences for knee injury risk resulting from these APA failures.

Materials and methods

Participants

Using data from the literature evaluating unanticipated movements (Brown et al., 2009), the sample size was estimated to achieve 80% statistical power with an alpha level of 0.05. Accordingly, thirteen male amateur football players (age: 24 ± 3 years old; height: 1.79 ± 0.03 m; mass: 73.8 ± 7.4 kg; football experience: > 10 years in the 5th-7thGerman league) participated in the study. Prior to testing, all participants were informed about possible risks and gave written informed consent. Participants did not have a previous history of serious knee injury or any current knee pain. All procedures were approved by the local ethics committee.

Protocol

Football players were asked to perform three different tasks in a randomized order, including a cutting manoeuvre to 45° , a crossover to -20° and a straight run with an

approach running speed of 5 ± 0.2 m.s⁻¹. The tasks were performed on a force plate and were followed by a maximal sprint over a 4m distance.

The direction of the movement was indicated by a light signal occurring at different times before the left foot contacted the force plate. The first condition was anticipated (Ant), meaning that participants already knew which light would turn on before starting to run. For this condition the light stimulus appeared 850ms before ground contact. The three other cutting conditions were performed without this knowledge, while the light stimulus was presented 850ms, 600ms and 500ms before ground contact. The rationale for these delays was determined during pilot measurements. 850ms was considered long enough to prepare the movement in a similar manner to the Ant condition. In this condition the light stimulus appeared approximately 3 steps (during right foot contact) before the change of direction. 600ms was felt by the participants to be a typical time constraint comparable to game situations and the signal occurred during the initial contact of the left foot two steps prior to changing the direction. From this value, we decreased the time available until players started to fail in the task execution, but not in more than 20% of the trials. In this condition (i.e. 500ms condition), the light stimulus occurred during the push off phase of the left foot contact two steps prior to the change of direction.

The order of the four time conditions was randomly assigned over the 13 participants. Participants performed the movements on an artificial football turf (Ecofill®, Mondo S.p.A., Alba, Italy) while wearing the same neutral football shoe (Predator, Adidas, Herzogenaurach, Germany). All participants were used to such movements due to their football practice and were also familiar with the light stimulus procedure, as they had already participated in studies using this testing setup.

During the present study, participants had to perform about 80 running and cutting movements to ensure eight successful 45° cutting manoeuvres for each time condition.

Participants had at least 30 seconds recovery after each trial but could rest as long as they wanted to avoid the onset of fatigue.

The 45° cutting manoeuvre was the only movement to be further analyzed due to its relevance when investigating performance and injury aspects of changing direction tasks (see introduction). A trial was defined as successful if the approach speed was reached, the left foot hit the force plate and the sprint was conducted in the direction of the light stimulus already one step after the force plate.

Material

The approach running speed was measured over the last 3m before the force plate (Timer S3, Alge-Timing, Palling, Germany) and the sprint velocity over the first 3m after the force plate were recorded by means of light switches (M18 series, Panasonic Electric Works Europe AG, Holzkirchen, Germany).

The visual light stimulus was triggered automatically via a light switch (M18 series, Panasonic Electric Works Europe AG, Holzkirchen, Germany), triggered during the approach run. The three lights were placed at eye level in the directions of the three tasks, 7m away from the forceplate.

Three-dimensional head, trunk and leg kinematics were recorded using reflective skin markers (\emptyset 14mm) placed with self-adhesive tape on anatomical landmarks of the participants' head, trunk, pelvis and both right and left legs. Specifically, markers were placed around the head (four markers), on the suprasternal notch and the transition between the body of sternum and the xiphoid process as well as on the T6 vertebra, on the anterior and posterior superior iliac spines, on the great trochanter, medial and lateral epicondyle of the knee, tibia (two markers) and the medial and lateral malleolus of the left leg, and on the posterior, medial and lateral aspects of the heel cup as well as the toe of both feet. This marker placement was based on previously published

articles for the head (Sreenivasa et al., 2008) and the lower limb (Fleischmann et al., 2010). The marker positions for the trunk segment were developed based on the conclusions reported by Leardini, Biagi, Belvedere and Benedetti (2009). Markers were captured with a 12-camera motion analysis system (Vicon V-MX, VICON Motion Systems Ltd., Oxford, UK) at a sampling frequency of 200 Hz. A static trial with the subject standing in a pre-defined neutral position was used to define the kinematic model and to calculate segment lengths and joint centres (Grood & Suntay, 1983; Wu et al., 2002). Joint kinematics in three rotational degrees of freedom were determined using an yxz Euler rotation sequence of the respective segment coordinate system. Marker trajectory and ground reaction force (BP600900, AMTI, Watertown, USA) signals were both filtered with a low pass Butterworth filter (4th order, 20 Hz cut-off frequency) prior to calculating external joint moments with a standard inverse dynamics approach.

Data analysis

Kinematic parameters were first investigated at the end of the right foot contact, i.e. one step prior to the change of direction, as the body posture at this moment would represent the APAs and would also help to understand the organization of the transition phase between APAs and the moment of the change of direction. The right heel strike and toe off were determined based on the peak vertical acceleration signal of the heel marker and toe marker, respectively. Head rotation, trunk rotation and lateral trunk flexion with respect to the global coordinate system as well as step width were calculated (for positive orientation see Figure 1).

Then the kinematic parameters were analyzed at the time of the peak knee abduction moment during the left foot contact during the cutting manoeuvre, as this is a relevant parameter associated with knee injury (Hewett et al., 2005). Again, head rotation, trunk rotation and lateral trunk flexion as well as step width were determined. In addition, the foot progression angle was defined as the rotation of the calcaneus in relation to the global coordinate system. Moreover, hip and knee joint moments in the frontal plane were analyzed.

**** Figure 1 near here ****

Statistics

The selected biomechanical parameters were averaged across eight trials for each subject in each cutting condition and served as the basis for the statistical analysis (SPSS 20.0, IBM SPSS Statistics, IBM Corporation, Armonk, NY, USA). After having confirmed that the data followed a normal distribution (Kolmogorov-Smirnov test), main effects of cutting condition (Ant vs. 850ms vs. 600ms vs. 500ms) on the dependent biomechanical variables were tested using a one-way analysis of variance (General Linear Model) with repeated measures. Pearson's correlation coefficient was used to determine the relation between lateral trunk flexion and peak knee abduction moment during the cutting manoeuvre (Jamison, Pan, & Chaudhari, 2012). The level of significance was set at 0.05. If a statistically significant main effect was observed, LSD multiple comparison procedures determined where the differences occurred. All results are presented as group means \pm SD.

Results

One step before changing the direction, there was a significant influence of the cutting condition on head rotation (p=0.033), trunk rotation (p=0.002) and lateral trunk flexion (p<0.001), whereas step width was not reduced (p=0.081) (see Table 1).

In the cutting condition with 600ms the head was significantly less rotated to the right compared to both Ant and 850ms (p=0.033 and p=0.028, respectively), while higher trunk rotation to the left was found for both 600ms and 500ms compared to Ant and 850ms (p<0.026) and higher lateral trunk flexion values were reported for both 600ms and 500ms than Ant and 850ms (p<0.001). None of these parameters were significantly different between Ant and 850ms, as well as between 600ms and 500ms.

At the time of the peak knee abduction moment, there was a significant influence of the cutting condition on head rotation (p=0.015), trunk rotation (p=0.028) and lateral trunk flexion (p<0.001), whereas step width and foot progression angle were not altered (Table 2).

During the cutting condition with 600ms the head was significantly less orientated towards the right compared to both Ant and 850ms (p=0.032 and p=0.018, respectively). The 500ms and 600ms cutting conditions yielded larger trunk rotation to the left than 850ms (p=0.036 and p=0.043, respectively). Compared to both Ant and 850ms, lateral trunk flexion values were significantly higher for 600ms (p<0.002) and 500ms (p<0.001). Additionally, the lateral trunk flexion was higher for 500ms than 600ms (p=0.015). None of these parameters were significantly different between Ant and 850ms.

Mean values of the parameters dealing with the loading of the lower limb at the time of the peak knee abduction moment are reported in Table 3. Along with the reduction of the time to prepare the cutting manoeuvre, there was a significant increase of the posterior (p<0.001) and vertical ground reaction forces (p<0.001). The cutting condition significantly influenced both hip (p<0.001) and knee abduction moments (p<0.001). Moreover, the contact time was influenced by the cutting condition (p<0.001).

Again, none of these parameters were significantly different between Ant and 850ms. Compared to Ant and 850ms, posterior ground reaction force was significantly higher for 600ms (p=0.005 and p=0.024, respectively) and 500ms (p<0.001 for both), while 500ms even yielded a higher posterior ground reaction force than 600ms (p=0.04). The vertical ground reaction force during the cutting condition with 600ms was significantly higher than Ant and 850ms (p=0.003 and p=0.015, respectively). In the same manner, performing the cutting manoeuvre with 500ms resulted in higher vertical ground reaction forces than both Ant (p=0.001) and 850ms (p=0.006). The 500ms cutting condition yielded increased hip abduction moment compared to Ant (p=0.002) and 850ms (p=0.007), as well as increased knee abduction moment compared to Ant (p=0.001) and 850ms (p=0.003). The same observation could be made for 600ms, which, compared to Ant and 850ms, generated higher hip and knee abduction moments (p<0.009 and p<0.011, respectively). Compared to Ant and 850ms, contact time values were significantly higher for 600ms (p=0.007 and p=0.002, respectively) and 500ms (p<0.001 for both). Additionally, the contact time was longer for 500ms than 600ms (p=0.008).

To further understand the influence of lateral trunk flexion on knee abduction moment, variations from the Ant condition baseline in the three unpredictable cutting conditions for these two parameters were plotted together (Figure 2). Lateral trunk flexion significantly correlated with peak knee abduction moment (r=0.41; p=0.009).

Sprint velocity remained comparable over the four cutting conditions, ranging from $5.0\pm0.4 \text{ m.s}^{-1}$ for Ant to $4.9\pm0.3 \text{ m.s}^{-1}$ with a delay of 500ms.

Discussion

The primary finding of the present study was that APAs are modulated according to the time available to prepare a cutting manoeuvre. Participants relied on a higher lateral trunk flexion to perform cutting manoeuvres under limited time available. While this was an effective strategy to maintain the sprint performance, higher lateral trunk flexion was associated with increased knee abduction moment. Finally, as soon as the time available was sufficient (850ms), not knowing in advance in which direction one would have to cut did not influence APAs, knee joint loading or sprint performance.

Of the three main APA strategies proposed in the literature, lateral trunk flexion was the most influenced by the cutting condition. Head and trunk rotations were also influenced by the time available to prepare the cutting manoeuvre, whereas the step width regulation was not significantly altered.

With less time available, lateral trunk flexion increased by 10.3° (500ms vs. Ant) already one step prior to the cutting manoeuvre and by 8.4° at the time of the change of direction 150ms later. This finding is in agreement with data from previous studies (Houck et al., 2006; Patla et al., 1999). Lateral trunk flexion was even more increased in the present study compared to the $+3.7^{\circ}$ found by Houck et al. (2006) when participants performed a 50° cutting task under unpredictable conditions but with a lower approach velocity of 1.9 m.s⁻¹. The higher lateral trunk flexion can be seen as a strategy to move the CoM in the new direction. A neuromuscular explanation for this

increased lateral trunk flexion strategy could be the relative higher strength of the trunk and hip muscles compared to other rather weak muscles (e.g. ankle invertors/evertors) during the stance phase. Therefore, participants could rely more on their trunk than on any foot placement strategy.

Head and trunk rotations were influenced to some degree by the time restriction to prepare the cutting manoeuvre. With less time available, the head was less orientated towards the cutting direction and the trunk was even more rotated in the opposite direction at the time of changing the direction as well as one step before. The rotation of the trunk in the opposite direction has already been reported in the literature during cutting manoeuvers (Dempsey et al., 2007; Dempsey, Lloyd, Elliott, Steele, & Munro, 2009). The influence of the cutting condition on head and trunk rotations was limited, as for instance no significant difference was observed between the 500ms and Ant conditions at the time of the peak knee abduction moment or given that standard deviation values for the head (7° to 13°) and the trunk (7° to 11°) were large. The relatively small influence of the time available on these APAs further shows the weak importance of head and trunk rotation strategies during cutting manoeuvres.

The step width strategy depends on the foot placement. One step prior to changing the direction, a medial shift of the foot placement with respect to the CoM would allow the centre of mass to accelerate towards the new direction. However, this strategy tended to be less used under critical time conditions (< 600ms). Moreover, the subsequent foot contact when changing the direction was not modulated, i.e. the foot was not placed more laterally to increase the acceleration of the CoM in the cutting direction. This result is in agreement with Patla et al. (1999) and partially consistent with Wheeler and Sayers (2010) and Houck et al. (2006). Indeed, as soon as the change of direction was unpredictable, the first authors reported that the step width strategy was significantly less used one step prior to changing the direction and the latter

authors found a reduction of the step width at the time of the cutting manoeuvre. Moreover, less use of the step width strategy one step before the change of direction was associated with reduced lateral movement speed (Wheeler & Sayers, 2010). Therefore, the step width strategy does not seem to be the one to increase or to rely on during challenging cutting manoeuvres.

Accordingly, altering lateral trunk flexion is probably the most relevant postural strategy to successfully perform a cutting manoeuvre under unpredictable conditions and to maintain the subsequent sprint performance at the same level.

Despite obvious main effects of the cutting condition on APAs, it is worth noting that further statistical analysis revealed no significant difference between Ant and 850ms. Accordingly, not knowing in advance which cutting manoeuvre will have to be executed does not influence APA strategies as long as the time available to prepare the movement is long enough. Under the present conditions, i.e. 5m.s⁻¹ approach velocity and 45° cut angle, a time of 850ms (3 steps prior to the change of direction) was enough to use postural strategies comparable to those observed under predictable conditions.

Whereas lateral trunk flexion was increased during successful cutting manoeuvres under limited time to prepare the movement, the overall leg loading as well as the joint loading increased. Indeed, posterior and vertical ground reaction forces at the time of the peak knee abduction moment (roughly 20-25ms after foot strike) were significantly higher for both the 600ms and the 500ms cutting conditions. This higher loading of the leg could increase the difficulty of the task, requiring significantly longer contact time and explaining also why 20% of the cutting manoeuvres with 500ms time available were not successful.

Moreover, hip and knee joint moments increased in the frontal plane as soon as the time available decreased to 600ms. This observation is in agreement with previous results showing increased joint loading under unpredictable conditions (Besier et al., 2001; Brown et al., 2009), although Dempsey et al. (2009) reported no significant influence of unpredictability on knee joint moments under conditions comparable to the present study (approach velocity, cutting angle and light stimulus timing). The large peak knee abduction moment values (up to 1.24 Nm.kg⁻¹) are consistent with recently published data (Vanrenterghem, Venables, Pataky, & Robinson, 2012) and underline the high loading of the knee and the possible risk for knee injury. The substantial new information provided by the present study is that not only cutting angle or approach velocity or even the unpredictability about the cutting condition influence knee joint loading but also the time available to prepare the cutting manoeuvre.

The increased lateral trunk flexion due to the reduction of the time available explained approximately 17% of the variance in peak knee abduction moment and should therefore be considered as an important parameter when investigating knee injury mechanisms (Figure 2). This association confirms previous observations dealing with the mechanical coupling between trunk and knee joint in the frontal plane (Dempsey et al., 2009; Hewett & Myer, 2011; Houck et al., 2006; Jamison et al., 2012).

Thus, it can be concluded that altered APA strategies under unpredictable conditions are one factor leading to an increased knee joint injury risk during cutting manoeuvres, along with, for instance, less suitable neuromuscular activity of the knee joint muscles (Besier, Lloyd, & Ackland, 2003).

Accordingly, the aim of future studies could be to provide solutions for this excessive use of lateral trunk flexion. Reducing the use of this strategy would then probably need to be compensated by other anticipatory postural strategies to maintain the subsequent sprint performance at the same level. For instance it is known that head and trunk rotation strategies tend to be reduced with maturation (Vallis & McFadyen, 2005). Therefore, training these strategies again to improve the re-orientation of the whole body based on a head and trunk rotation might be a relevant solution. Another solution could be a modified foot placement. Dempsey et al. (2009) have already reported a reduction of knee joint loading associated with a specific whole body cutting technique, characterized by a medial shift of the foot together with a more neutral lateral trunk flexion at the time when changing the direction. However, even if a more externally rotated foot placement, i.e. the foot progression angle, might be a strategy to reduce knee joint frontal plane loading (Fleischmann, Gehring, Mornieux, & Gollhofer, 2010; Sigward & Powers, 2007), this parameter was not influenced by the cutting conditions in the present study. Therefore, modulation of the foot rotation does not seem to be an appropriate strategy to prepare a cutting manoeuvre under limited time available.

It has to be emphasized that any cutting technique modification through a training intervention would probably be more effective if attention is brought to the step prior to the change of direction, whichever strategy, i.e. head rotation, trunk rotation or step width regulation, is trained.

The relevance of the present results can be transferred to daily football training. Firstly, training should put emphasis on decision making situations, where players have to identify ball trajectories, teammate or opponent displacements that are not pre-defined and make the appropriate decision accordingly (relevant timing and direction of the pass or displacement). Secondly, training should focus on situations where players experience one against one situations (either by attacking or defending) and where changes of direction are required. During these situations, players would focus on their trunk rotation and the lateral trunk flexion to operate such cutting manoeuvres. The

upper body should not only be kept straight but orientated towards the new direction of the cutting manoeuvre. Moreover, players should pay attention to the alignment of the leg and the upper body already one step prior to the change of direction.

To conclude, this study provides a detailed biomechanical and functional analysis of anticipatory postural adjustment strategies during cutting manoeuvres in football. From the variables analysed in the present study, increasing lateral trunk flexion is the most effective strategy to successfully perform a cutting manoeuvre when less time is available to prepare the movement. But this is also associated with increased knee injury risk. Considering knee injury as a serious issue in football, training programs need to improve anticipatory postural adjustments to reduce injury risk and possibly enhance performance.

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Tables

	Ant	850ms	600ms	500ms
Head rotation (°)	11.1 ± 9.1	10.9 ± 9.9	6.5 ± 10.5 * ^a	6.9 ± 7.1
Trunk rotation (°)	-7.1 ± 8.4	-7.0 ± 8.5	-10.8 ± 9.3 *a	-11.1 ± 7.3 *a
Lateral trunk flexion (°)	1.9 ± 5.2	3.6 ± 4.7	9.8 ± 5.4 * ^a	12.2 ± 5.7 *a
Step width (m)	$\textbf{-0.24} \pm 0.06$	$\textbf{-0.27} \pm 0.08$	$\textbf{-0.23} \pm 0.09$	-0.21 ± 0.11

Table 1

<u>Table 1:</u> Mean \pm SD values of the anticipatory postural strategies one step prior to the change of direction for the four cutting manoeuvre conditions (Ant, 850ms, 600ms, 500ms). Positive rotation values are orientated to the cutting direction, positive lateral flexion values are towards the left and negative step width values define a medial foot placement.

*^a significant differences compared to Ant and 850ms cutting conditions (p<0.05)

Table	2
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	Ant	850ms	600ms	500ms
Head rotation (°)	18.0 ± 11.3	17.6 ± 13.1	13.3 ± 13.5 *a	13.5 ± 11.5
Trunk rotation (°)	-4.8 ± 11.0	-3.3 ± 11.1	-7.3 ± 10.3 * ^b	-8.8 ± 9.9 * ^b
Lateral trunk flexion (°)	5.3 ± 6.1	6.1 ± 6.4	10.4 ± 6.4 *a	$13.7 \pm 6.9 * a,c$
Step width (m)	0.36 ± 0.03	0.35 ± 0.04	0.36 ± 0.03	0.35 ± 0.03
Foot progression angle (°)	7.8 ± 7.8	9.2 ± 7.9	6.9 ± 9.7	6.3 ± 9.8

<u>Table 2:</u> Mean \pm SD values of the postural strategies at the time of the peak knee abduction moment for the four cutting manoeuvre conditions (Ant, 850ms, 600ms, 500ms).

Positive rotation values are orientated to the cutting direction, positive lateral flexion values are towards the left and positive step width values define a lateral foot placement.

* expresses a significant difference:

^a compared to Ant and 850ms cutting conditions

^b compared to the 850ms cutting condition

^c compared to the 600ms cutting condition

Table	3
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	Ant	850ms	600ms	500ms
Posterior force (N.kg ⁻¹)	5.42 ± 2.51	6.11 ± 2.56	7.38 ± 2.25 * ^a	8.03 ± 2.16 * ^{a, c}
Vertical force (N.kg ⁻¹)	15.8 ± 5.9	17.1 ± 7.0	19.7 ± 5.7 * ^a	20.8 ± 5.9 * ^a
Hip abduction moment (Nm.kg ⁻¹)	2.01 ± 0.78	2.20 ± 0.88	2.55 ± 0.74 *a	2.57 ± 0.81 *a
Knee abduction moment (Nm.kg ⁻¹)	1.00 ± 0.48	1.04 ± 0.48	1.21 ± 0.47 *a	1.24 ± 0.49 *a
Contact Time (s)	0.22 ± 0.03	0.22 ± 0.03	$0.24 \pm 0.03 *^{a}$	0.25 ± 0.04 * ^{a, c}

<u>Table 3:</u> Mean \pm SD values of the ground reaction forces (posterior and vertical), hip and knee abduction moments at the time of the peak knee abduction moment and of the contact time for the four cutting manoeuvre conditions (Ant, 850ms, 600ms, 500ms).

* expresses a significant difference:

^a compared to Ant and 850ms cutting conditions

^c compared to the 600ms cutting condition

Figures captions

<u>Figure 1:</u> Schematic representation of one subject performing the 45° cutting manoeuvre to the right in response to the grey light stimulus. Figure A represents the end of the right foot contact, one step prior to the change of direction and Figure B the time of the peak knee abduction moment during the left foot contact.

Positive rotation values of the head, trunk and foot progression angle are orientated towards the cutting direction. Positive lateral trunk flexion values indicate a tilt of the trunk to the left. Positive step width values define a lateral foot placement with respect to the vertical projection of the hip joint centre.

<u>Figure 2:</u> Linear regression between peak knee abduction moment and lateral trunk flexion during the 45° cutting manoeuvres. Values represent the difference from the Ant condition for the 850ms (black diamonds), 600ms (grey circles) and 500ms (grey triangles) cutting conditions.



